

Maximum Lego Ev3 Building Mindstorms

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```
The detected color is looked up in # the action map. new_action = ACTION_MAP.get (color_sensor.color ()) # If the color was found, beep for 0.1 seconds and then change the # action depending on which color was detected. if new_action is not None: action_timer.reset ev3.speaker.beep (1000,-1) while action_timer.time < 100: yield ev3 ...
```

Gyro Boy — ev3-micropython 2.0.0 documentation

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